

#FABRICADEMY2021 TUTORIALS

SENSING & OUTPUTS

ATTINY TUTORIAL - PART 2

17-11-2021 | EMMA PARESCHI

Program

Attiny and Serial Monitor:

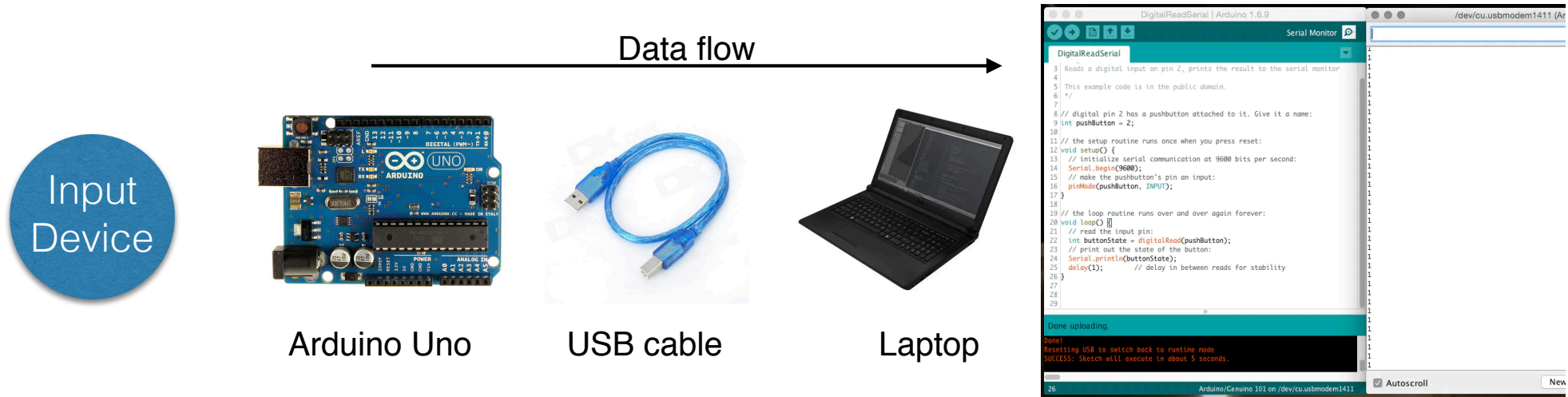
- How to use the Serial Monitor with the Attiny
- Circuits:
- Attiny reads a digital sensor
or
 - Attiny reads an analog sensor

Arduino Uno:

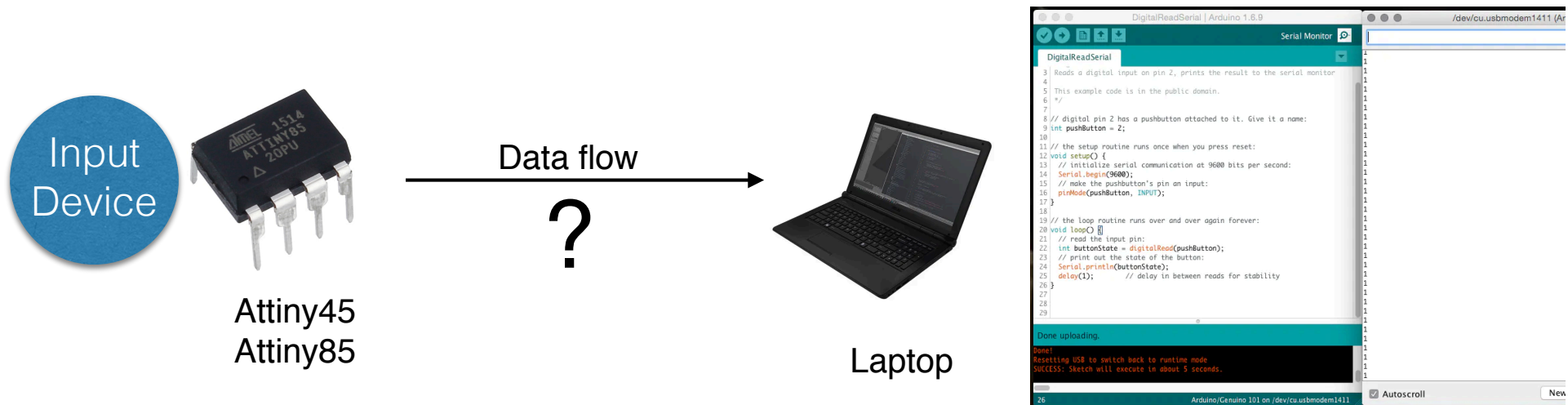
- Capacitive Sensor
- Circuits:
- Arduino Uno and Capacitive Sensor
 - Arduino Uno and 2 Capacitive Sensors
 - Arduino Uno, 2 capacitive sensors and 2 Leds
-
- PiezoResistive Matrix (Touchpad)
- Circuits:
- Arduino Uno and Matrix
 - Arduino Uno, Matrix and Neopixel

Attiny and Serial Monitor

How to send Data from the micro controller to PC

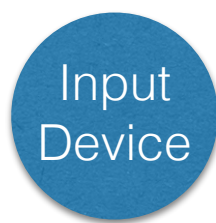


Arduino IDE and Serial Monitor



Arduino IDE and Serial Monitor

How to send Data from the micro controller to PC

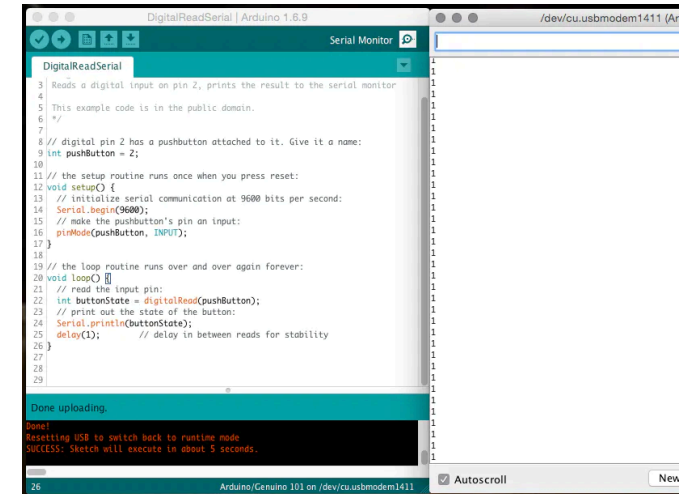


Attiny45
Attiny85

Data flow

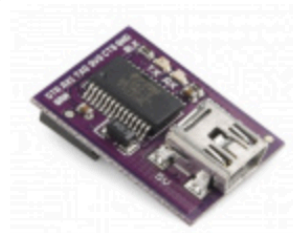
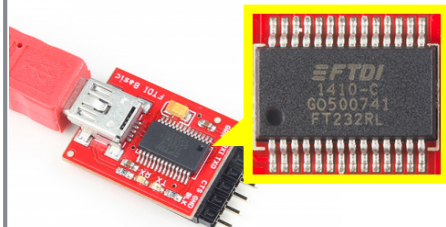


Laptop



Arduino IDE and Serial Monitor

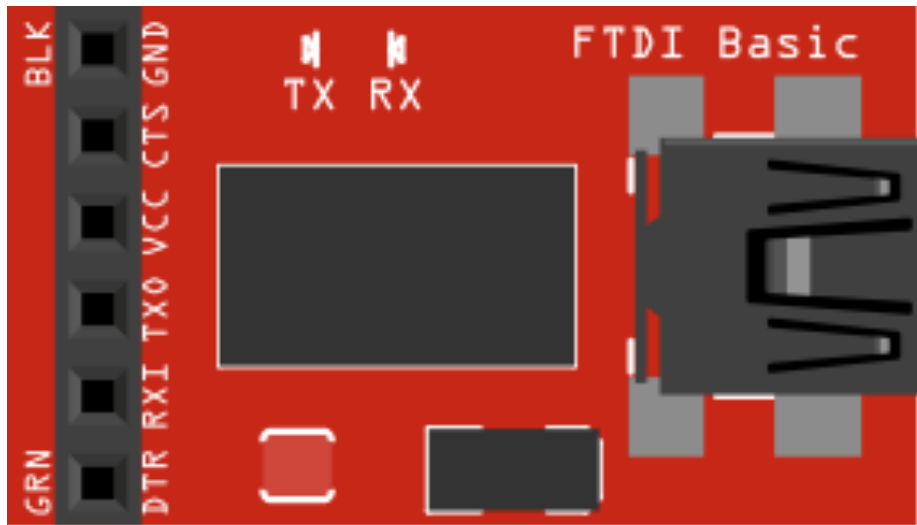
FTDI chip:



FTDI Chip and Cable

To be used they need drivers:
<https://learn.sparkfun.com/tutorials/how-to-install-ftdi-drivers/introduction>

FTDI board or cable



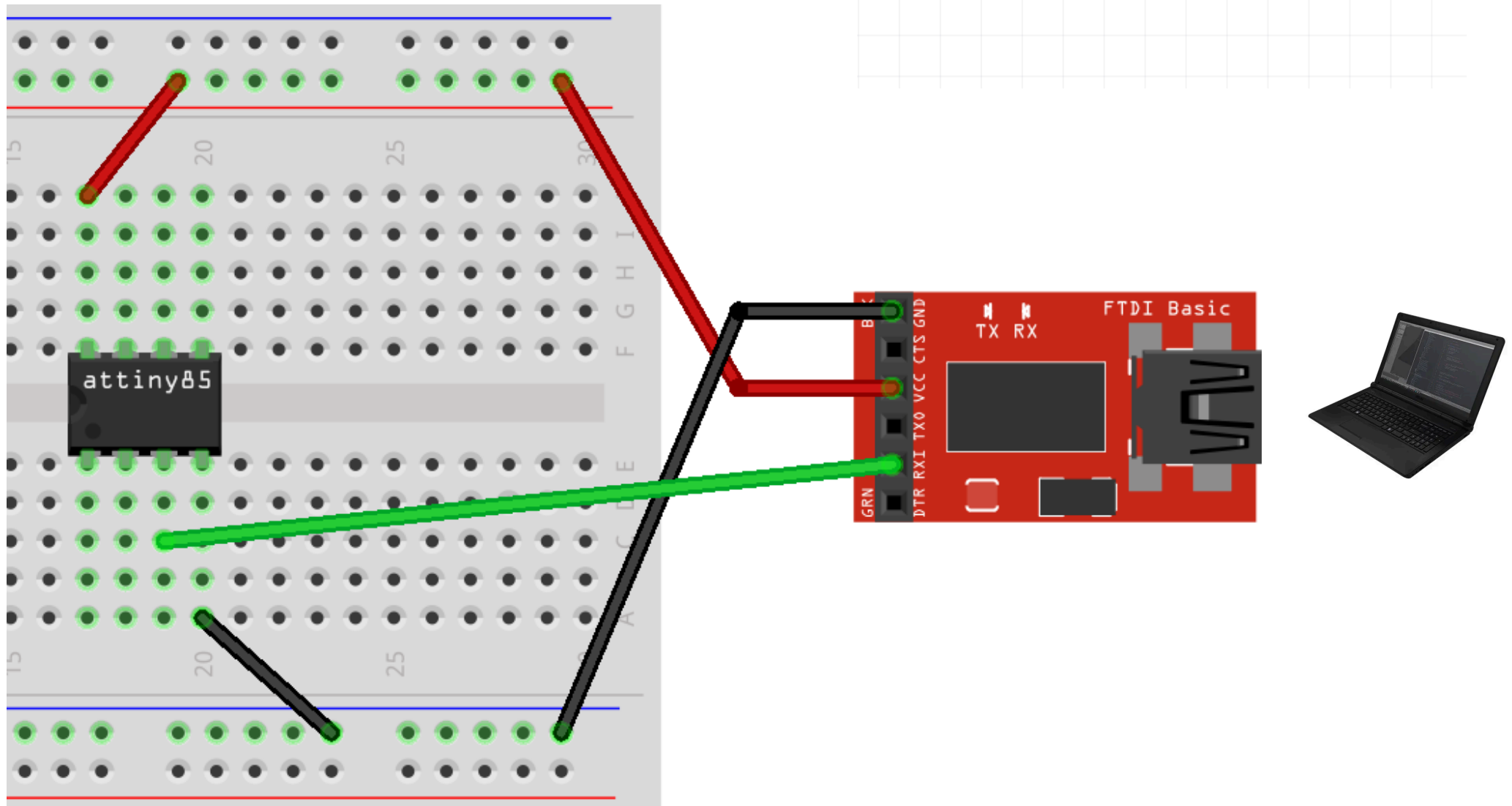
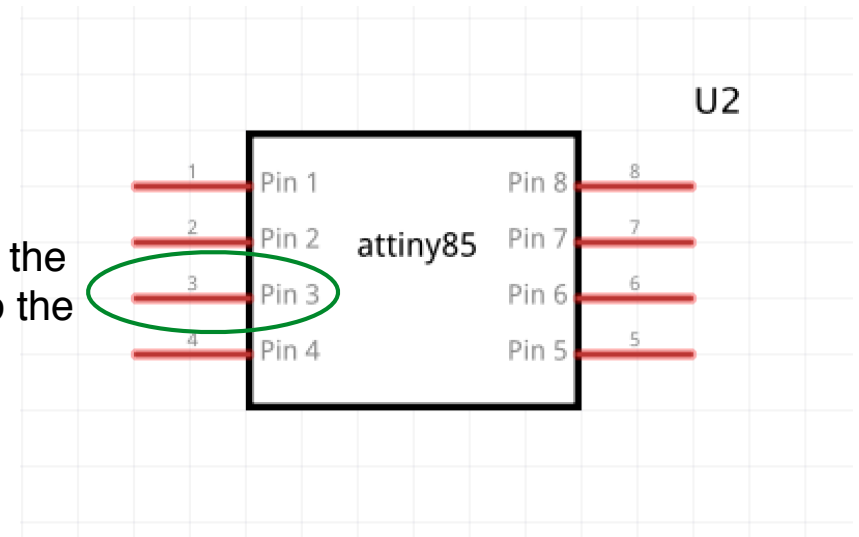
Pins that we will use:

- VCC
- GND
- RX

Check the reference of you hardware to know the orientation of the pins or use the multimeter to find GND and VCC

FTDI board or cable

We use pin 3 to send the data from the Attiny to the PC

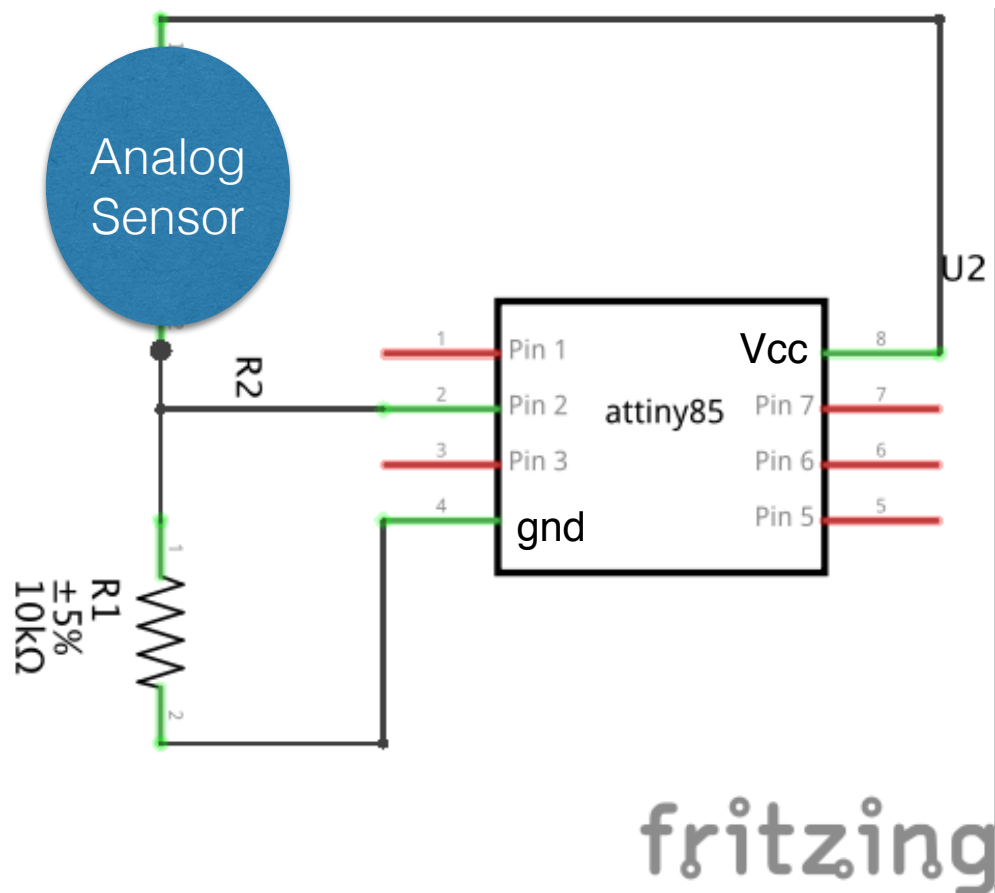


Steps

- 1. Decide what you want to measure
- 2. Connect the Attiny to your Programmer:
 - AVR programmer
 - Arduino UNO (make sure that the Arduino is uploaded with the ARduinoISP sketch).
- 3. Program the Attiny to read the sensor and send the data through Serial Communication.
- 4. Remove the programmer. Connect your Input device to the Attiny.
Connect the FTDI Board
- 5. Plug the FTDI board (or cable) and Open the Serial Monitor or Serial Plotter

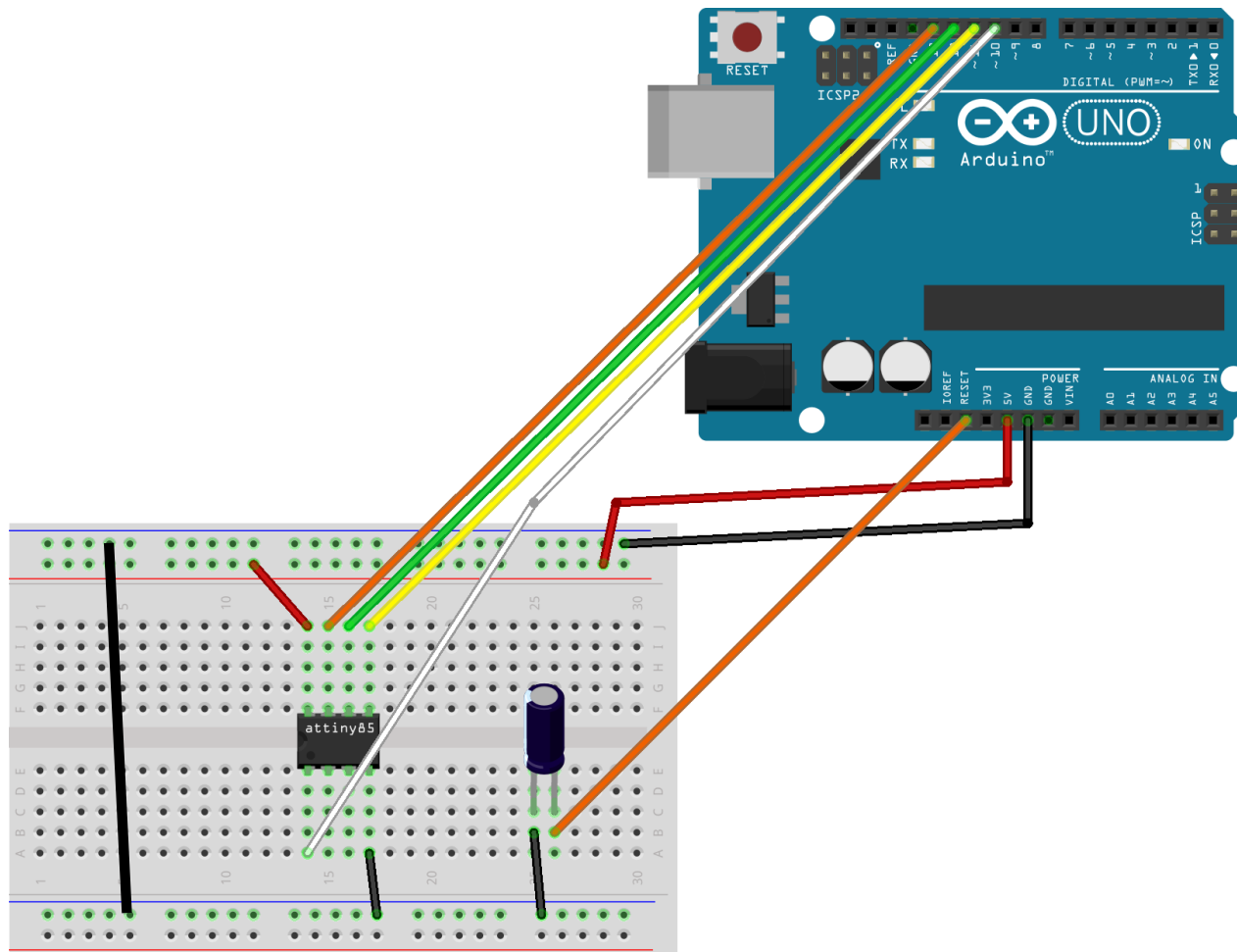
Step 1

- We want to read the data of an analog sensor



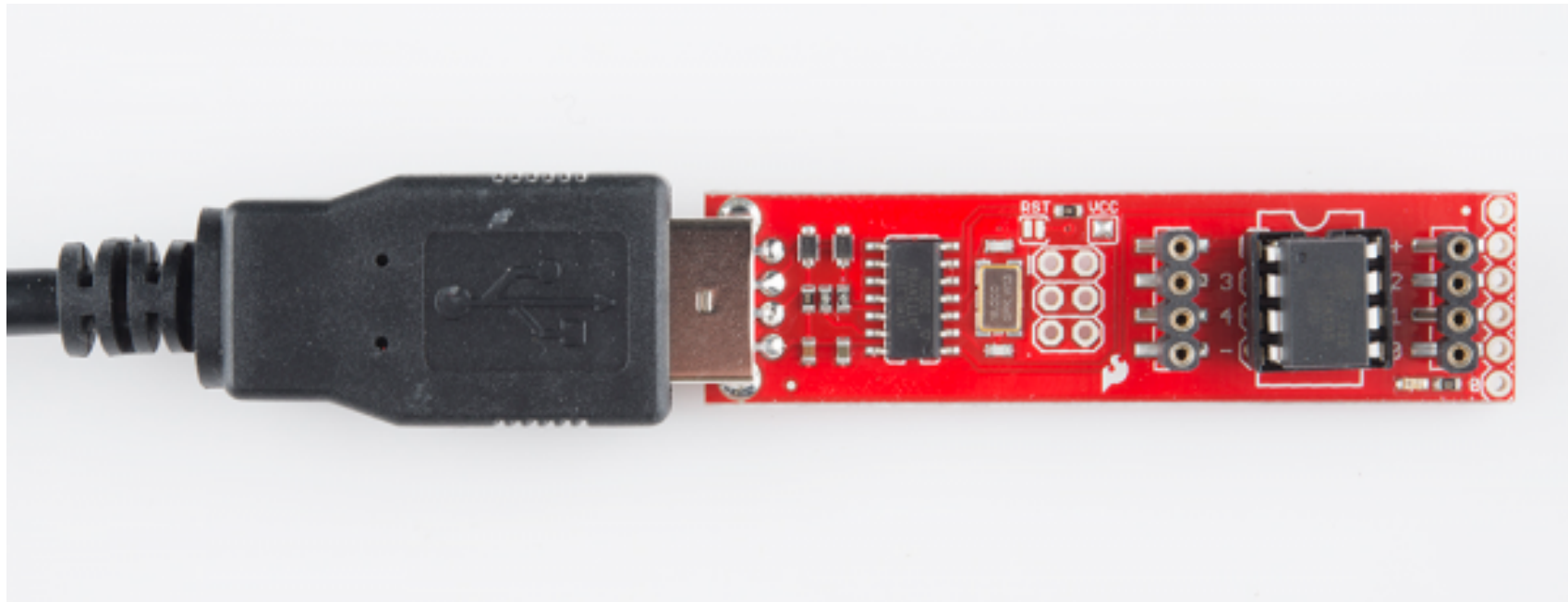
Step 2

- Connect the Attiny to your Programmer:
 - AVR programmer
 - Arduino UNO (make sure that the Arduino is uploaded with the ArduinoISP sketch)



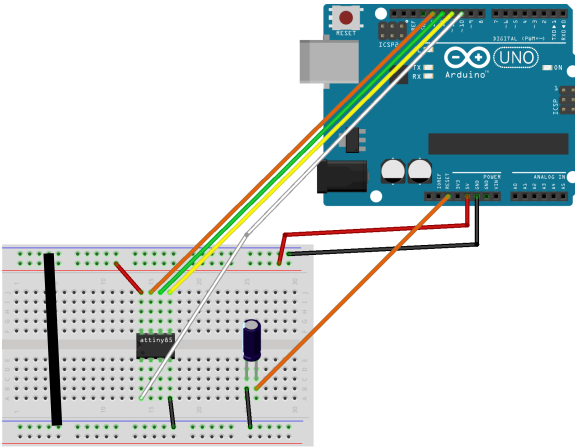
Step 2

- Connect the Attiny to your Programmer:
 - AVR programmer
 - Arduino UNO (make sure that the Arduino is uploaded with the ArduinoISP sketch)



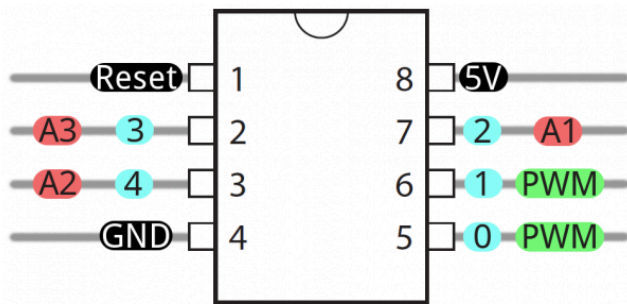
Step 3

- Program the Attiny to read the sensor and send the data through Serial Communication.



Few consideration that are needed to write the code:

- the sensor is connected to PIN 2 (Arduino pin3)
- the FTDI board is connected to PIN 3 (Arduino pin 4)



```
attiny_analog_sensor code: attiny_analog_sensor
#include <SoftwareSerial.h>

#define rxPin 11 //not used pin
#define txPin 4  //the pin we will use to transmit the data (it i

SoftwareSerial serial(rxPin, txPin);    //create the communicatio

int analog_sensor_pin = 3;  //change the pin, where the sensor is
int analog_sensor_value = 0;

void setup() {

  pinMode(rxPin, INPUT);
  pinMode(txPin, OUTPUT);
  pinMode(analog_sensor_pin, INPUT); //define the pin as INPUT
  serial.begin(9600);    //open communication

}

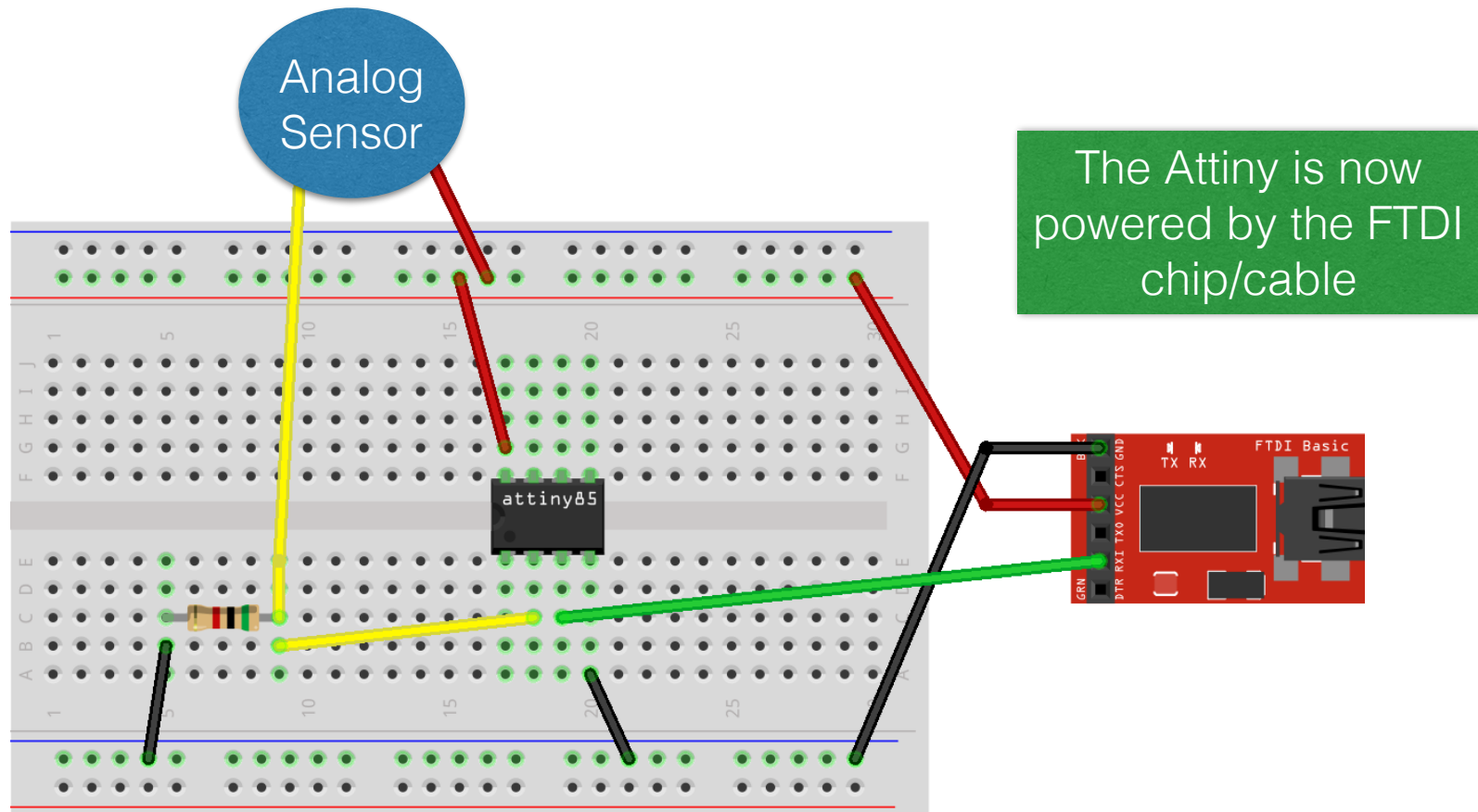
void loop(){

  analog_sensor_value = analogRead(analog_sensor_pin); // read the
  serial.println(analog_sensor_value); //print on Serial Monitor

  delay(100);
}
```


Step 4

- Remove the programmer.
 - Connect your Input device to the Attiny.
- Connect the FTDI Board

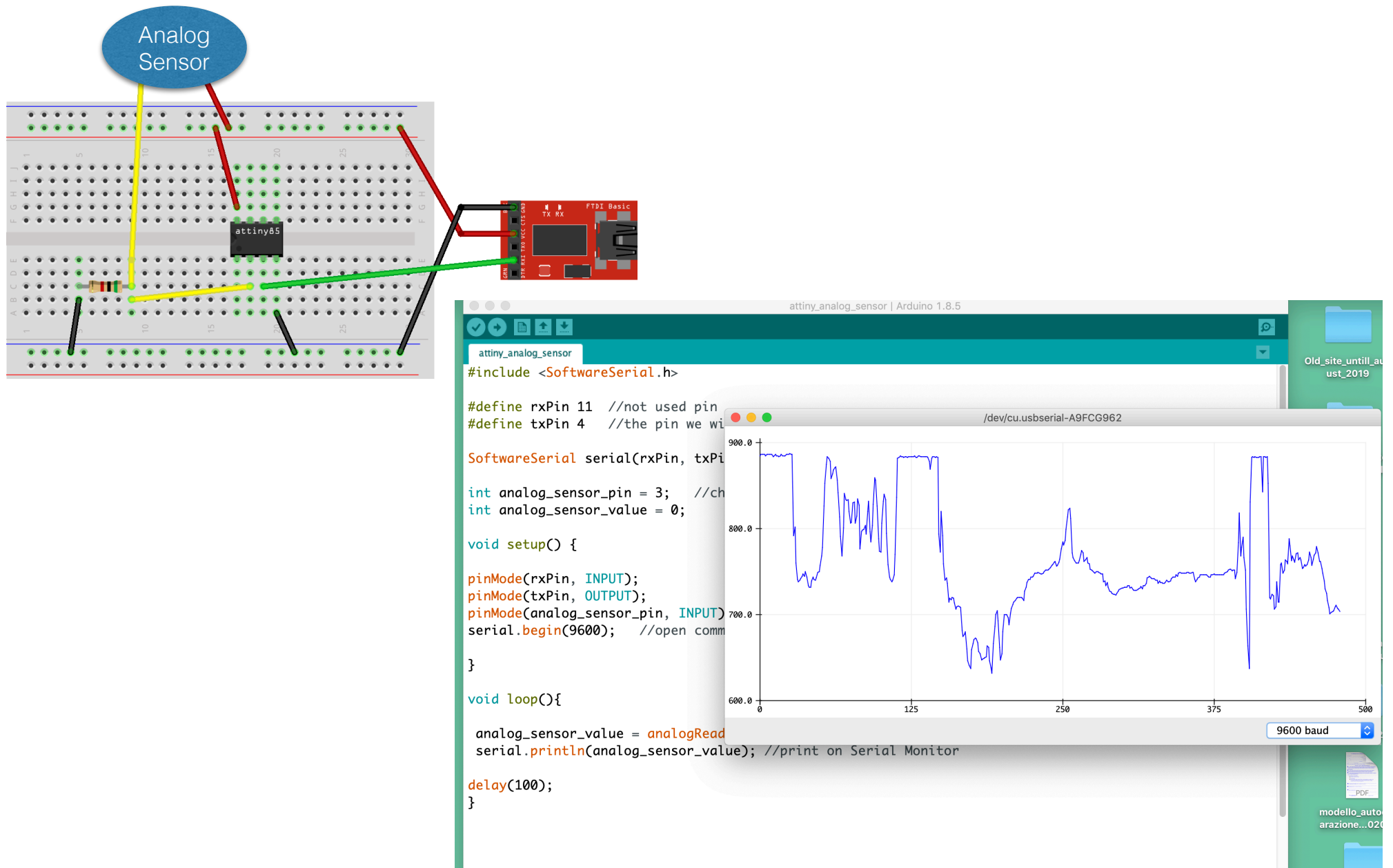


Few consideration that are needed to write the code:

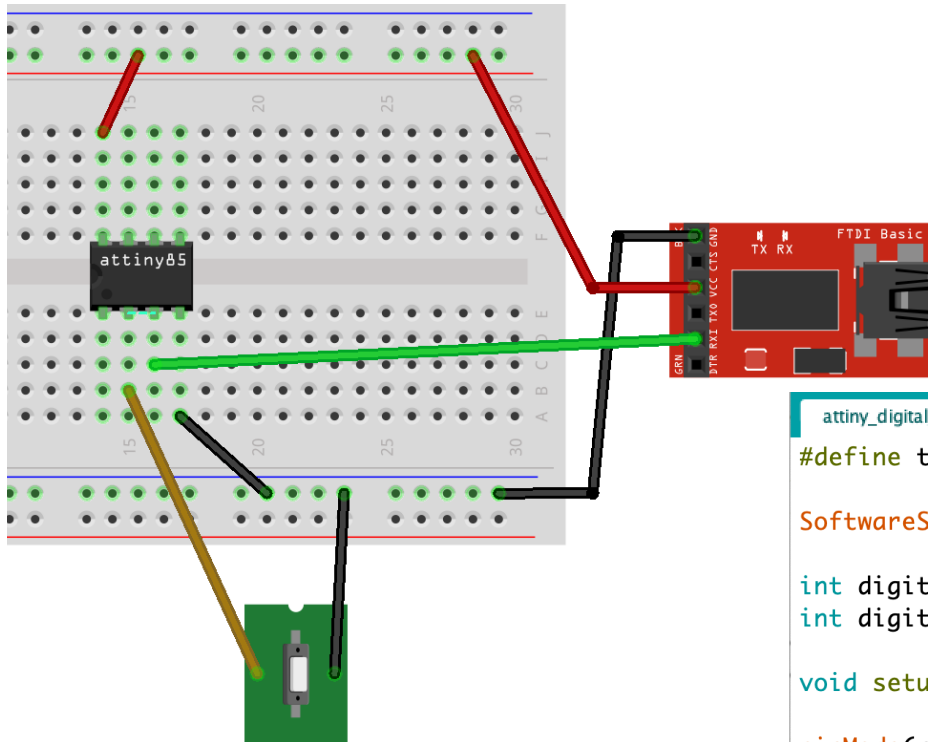
- the sensor is connected to PIN 2
- the FTDI board is connected to PIN 3

Step 5

- Plug the FTDI board (or cable), select the USB port and Open the Serial Monitor or Serial Plotter



Attiny and Digital Sensor



code: attiny_digital_sensor

```
attiny_digital_sensor
#define txPin 4

SoftwareSerial serial(rxPin, txPin);

int digital_sensor_pin = 3;    //change the pin, where the sensor is connected
int digital_sensor_value = 0;

void setup() {

  pinMode(rxPin, INPUT);
  pinMode(txPin, OUTPUT);
  pinMode(digital_sensor_pin, INPUT_PULLUP); //define the pin as INPUT
  serial.begin(9600);

}

void loop(){
  |
  digital_sensor_value = digitalRead(digital_sensor_pin); // read the sensor
  serial.println(digital_sensor_value);

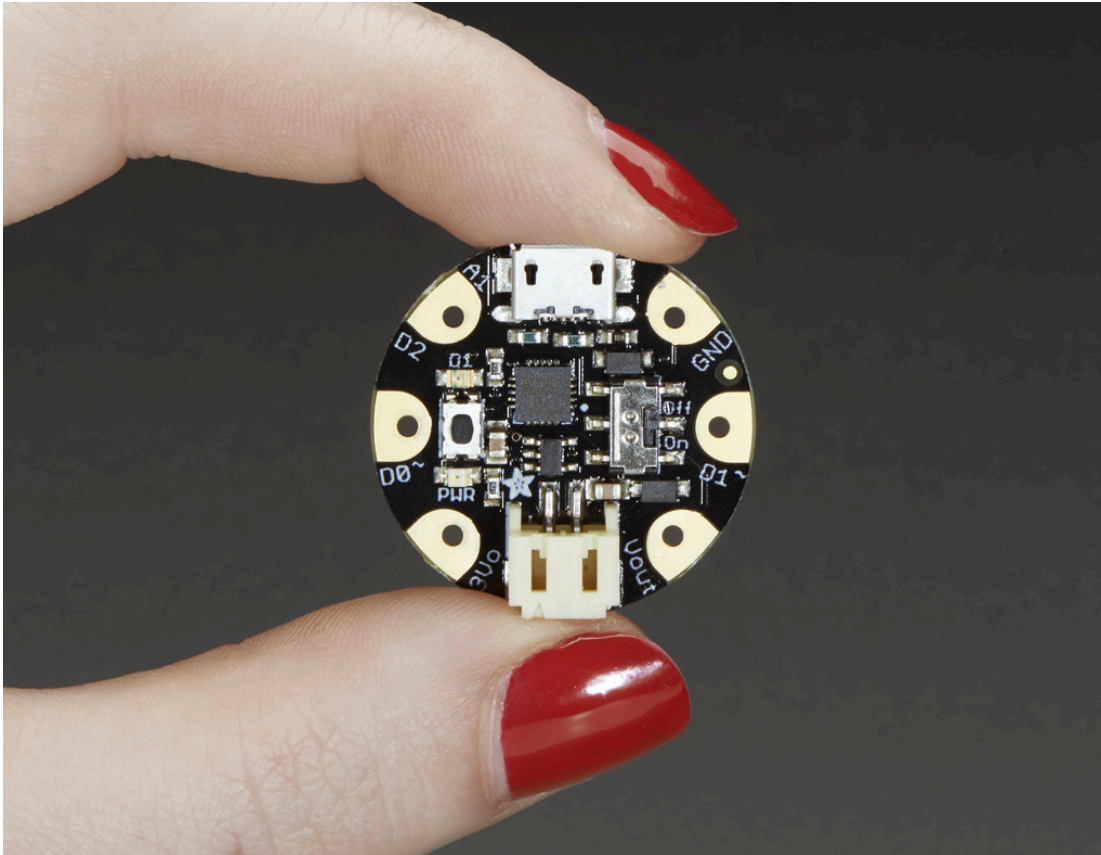
  delay(1000);
}
```

Few consideration that are needed to write the code:

- the sensor is connected to PIN 2 (Arduino pin3)
- the FTDI board is connected to PIN 3 (Arduino pin 4)

Gemma

Gemma



Adafruit's mini wearable microcontroller

It is an Attiny85 breakout board.

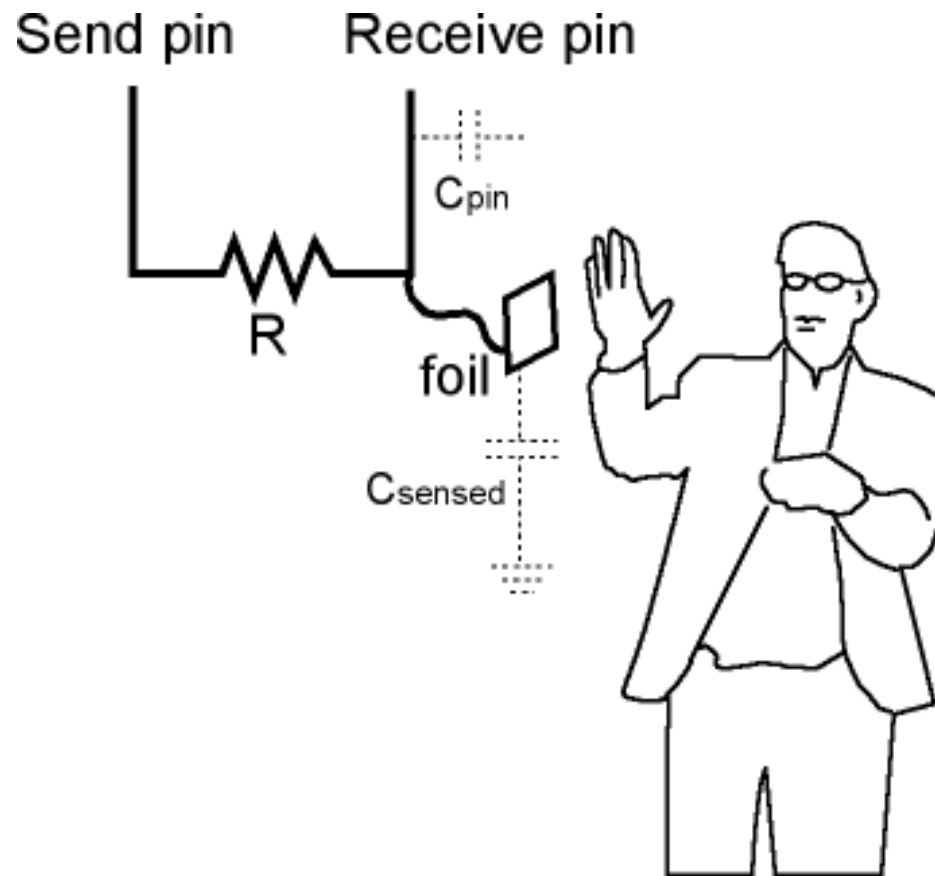
You can program it with just a USB cable.
No Need of Programmer!!!

It doesn't have a Serial port, you can't use the
Serial Monitor.

<https://learn.adafruit.com/introducing-gemma/introduction>

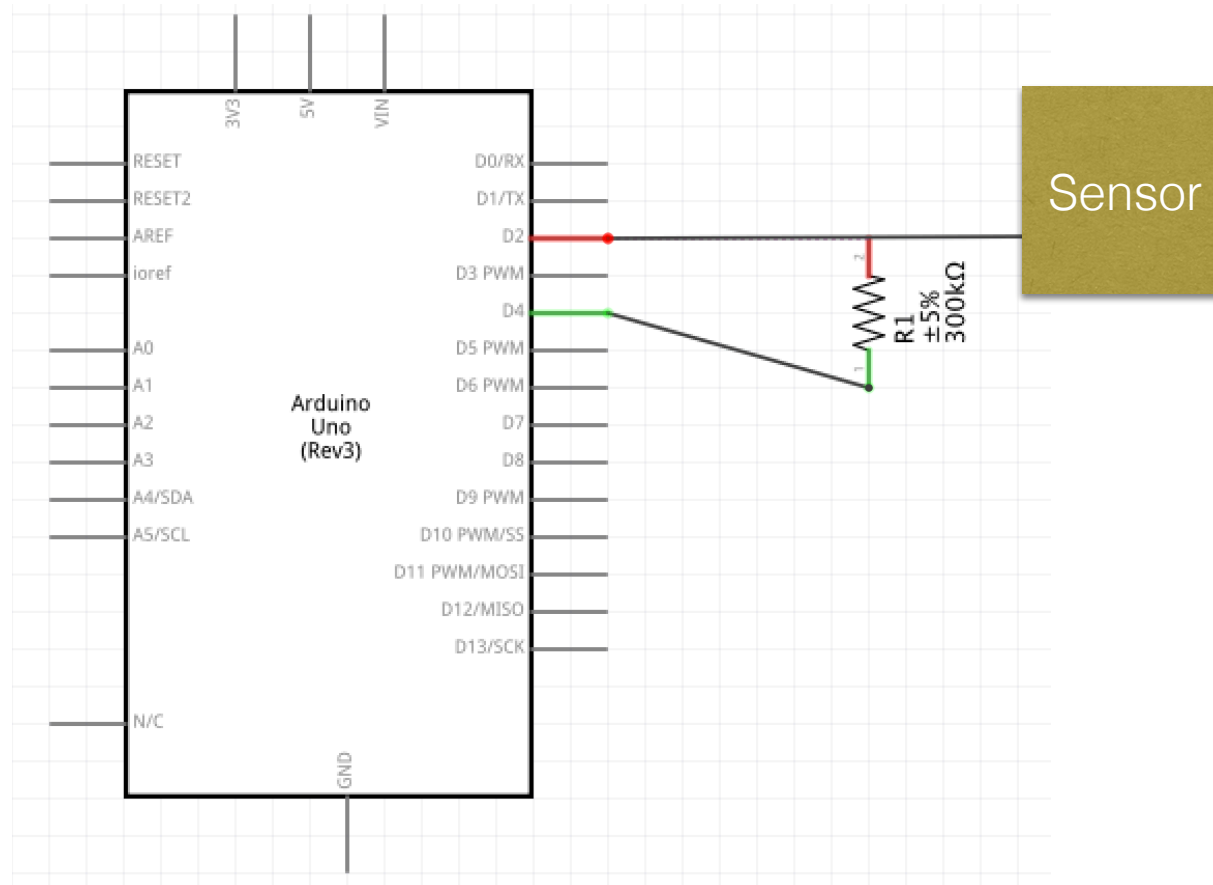
Capacitive Sensor

Capacitive Sensor

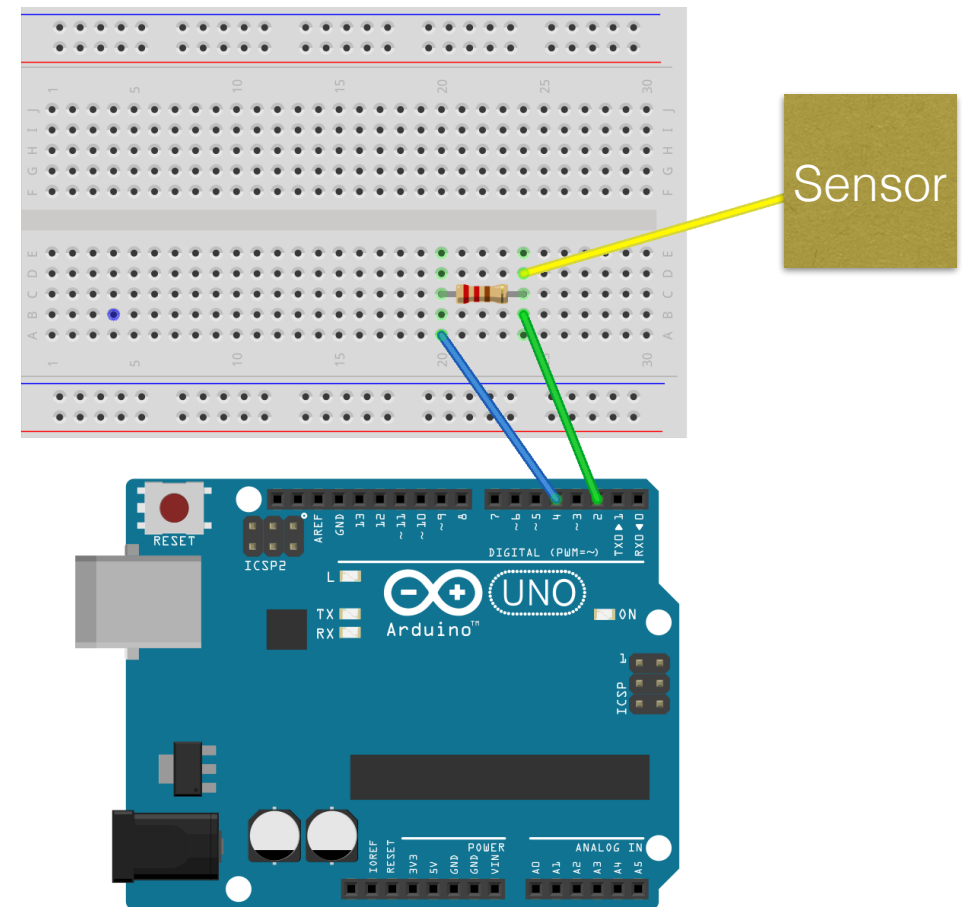
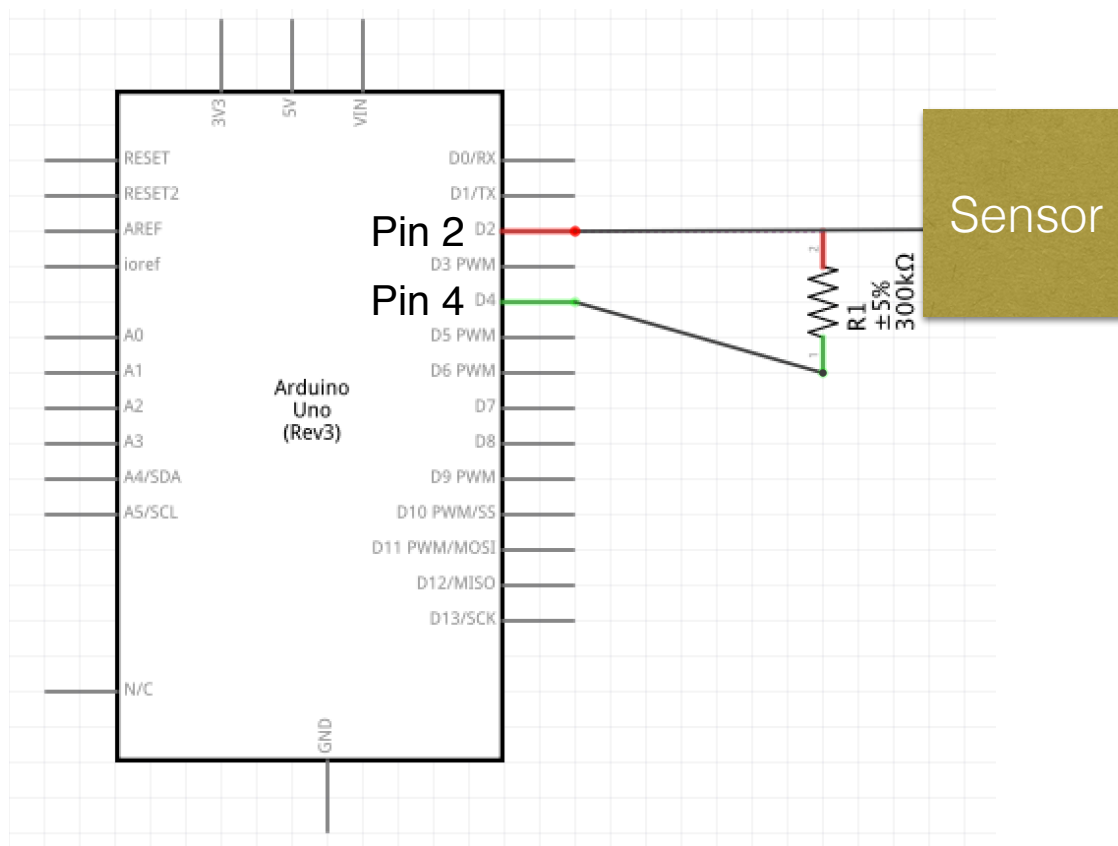


Reference page: <https://playground.arduino.cc/Main/CapacitiveSensor/>

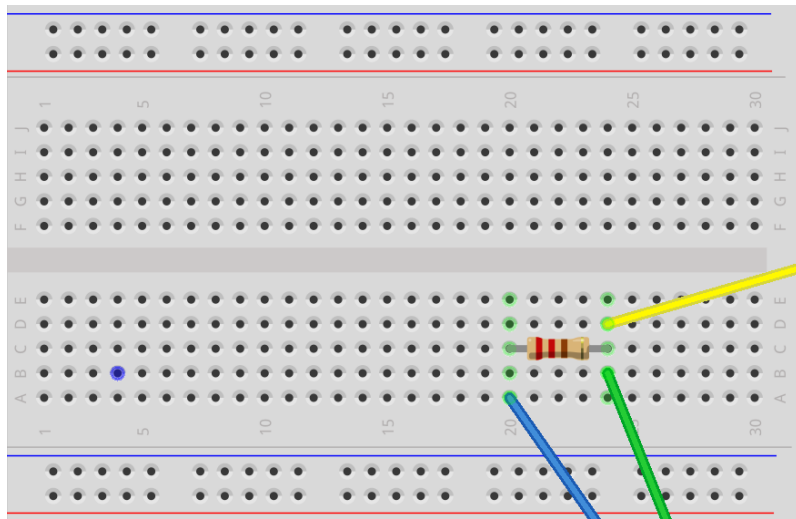
Capacitive Sensor - Circuit



Capacitive Sensor - Circuit



Capacitive Sensor - Circuit



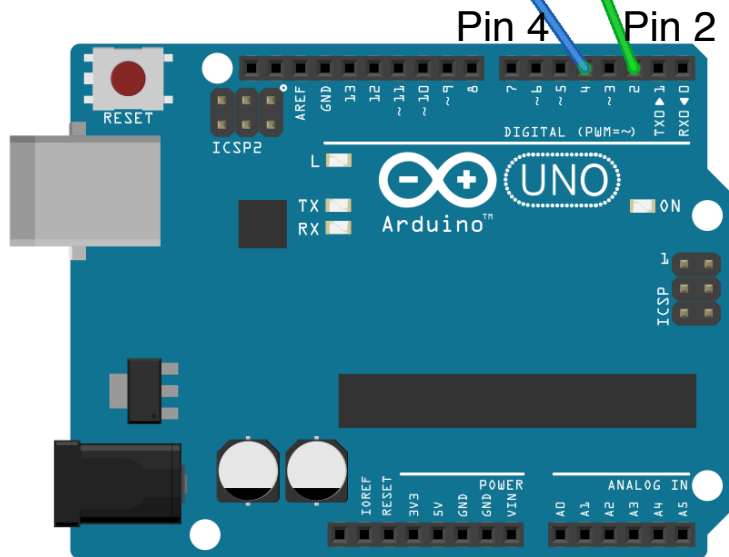
Sensor

Resistor Choice

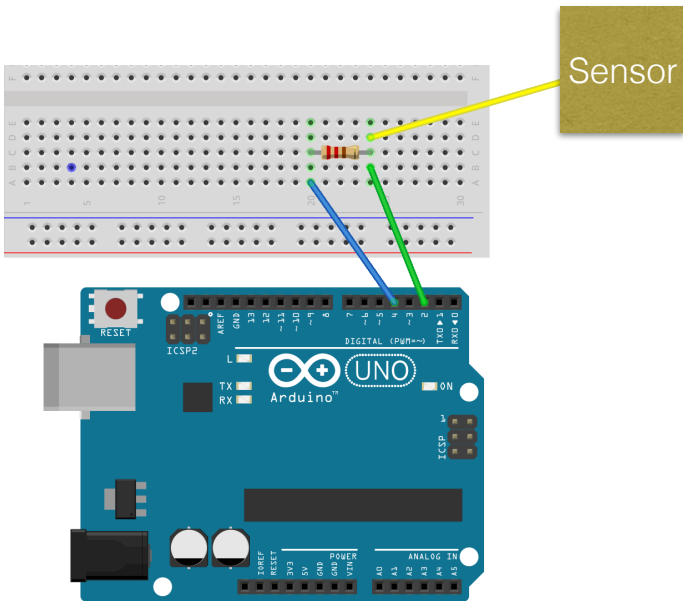
Here are some guidelines for resistors but be sure to experiment for a desired response.

- Use a 1 megohm resistor (or less maybe) for absolute touch to activate.
- With a 10 megohm resistor the sensor will start to respond 4-6 inches away.
- With a 40 megohm resistor the sensor will start to respond 12-24 inches away (dependent on the foil size). Common resistor sizes usually end at 10 megohm so you may have to solder four 10 megohm resistors end to end.
- One tradeoff with larger resistors is that the sensor's increased sensitivity means that it is slower. Also if the sensor is exposed metal, it is possible that the send pin will never be able to force a change in the receive (sensor) pin, and the sensor will timeout.
- Also experiment with small capacitors (100 pF - .01 uF) to ground, on the sense pin. They improve stability of the sensor.

Note that the hardware can be set up with one sPin and several resistors and rPin's for calls to various capacitive sensors. See the example sketch.



Capacitive Sensor - Code



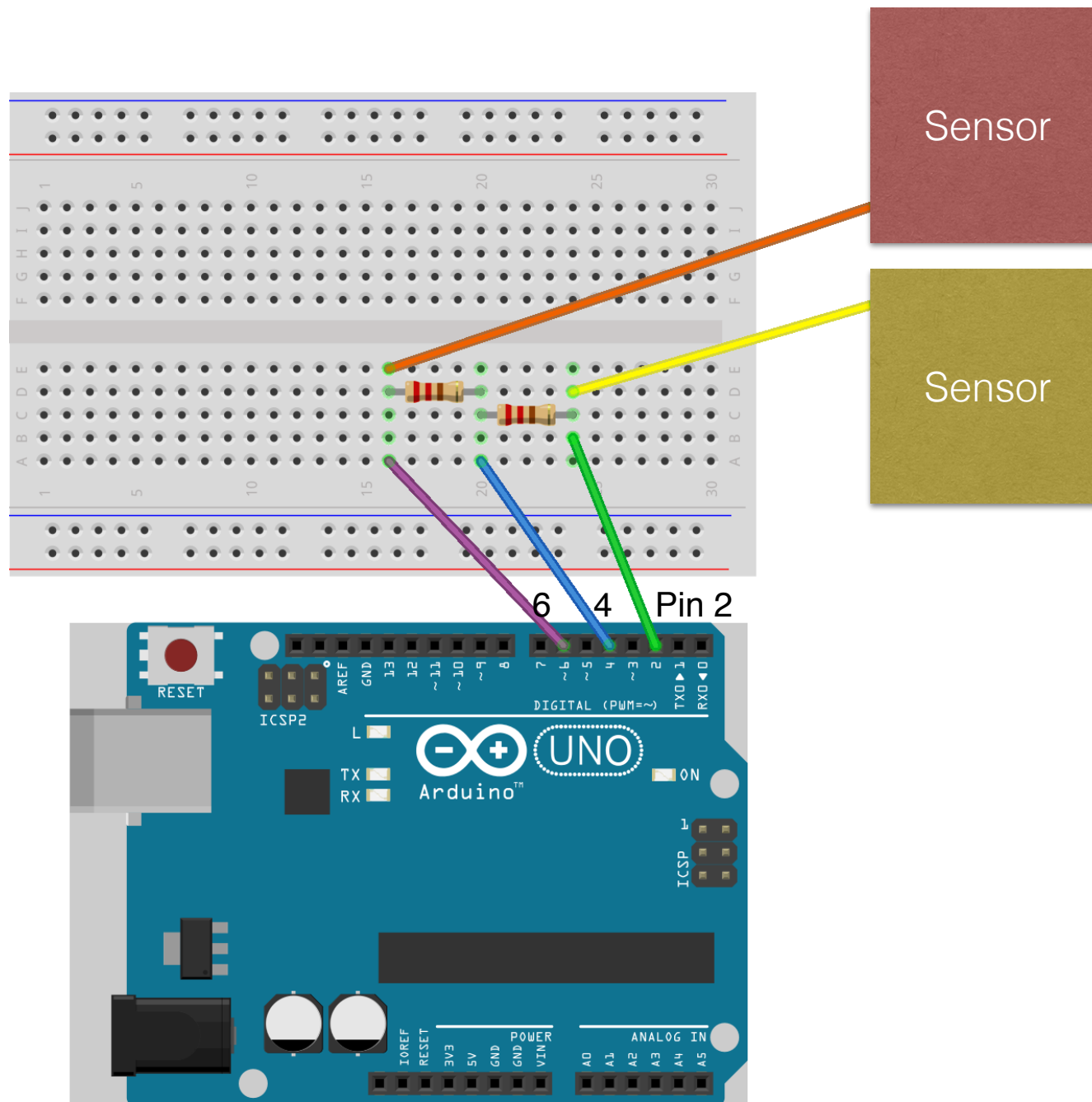
You need to install the library:
CapacitiveSensor

```
CapacitiveSensor §  
#include <CapacitiveSensor.h>  
  
/*  
 * Modified example from CapitiveSense Library Demo Sketc  
 * Paul Badger 2008  
 * Uses a high value resistor e.g. 10M between send pin c  
 * Resistor effects sensitivity, experiment with values,  
 * Receive pin is the sensor pin - try different amounts  
 */  
  
CapacitiveSensor cs_4_2 = CapacitiveSensor(4,2); // 1  
  
void setup()  
{  
  cs_4_2.set_CS_Autocal_Millis(0xFFFFFFFF); // turn off  
  Serial.begin(9600);  
}  
  
void loop()  
{  
  long total1 = cs_4_2.capacitiveSensor(30);  
  Serial.println(total1); // print ser  
  delay(10);  
}
```

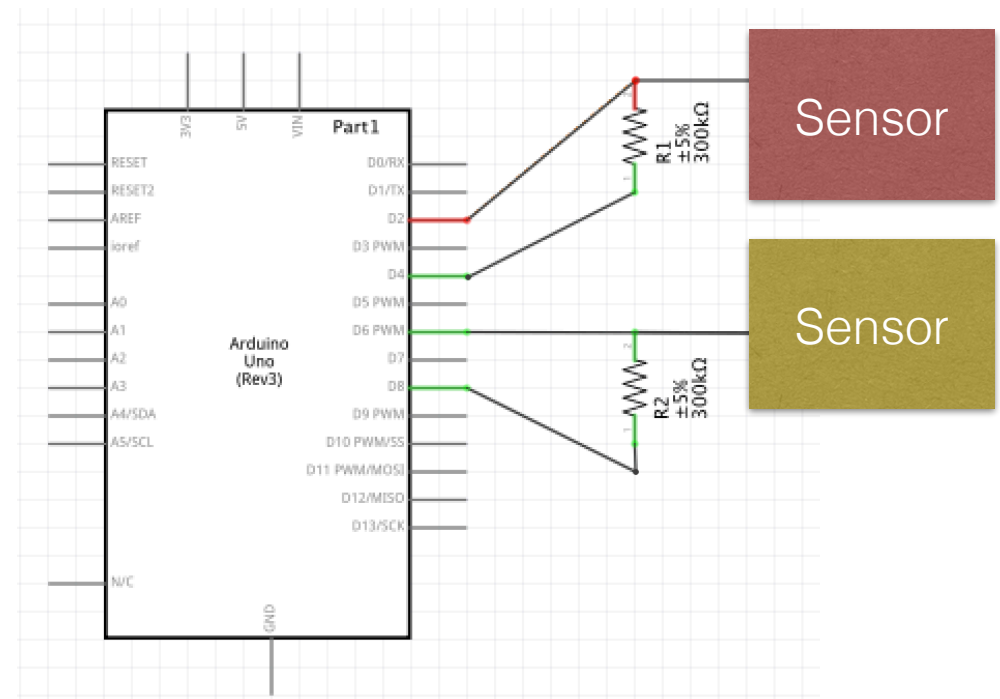
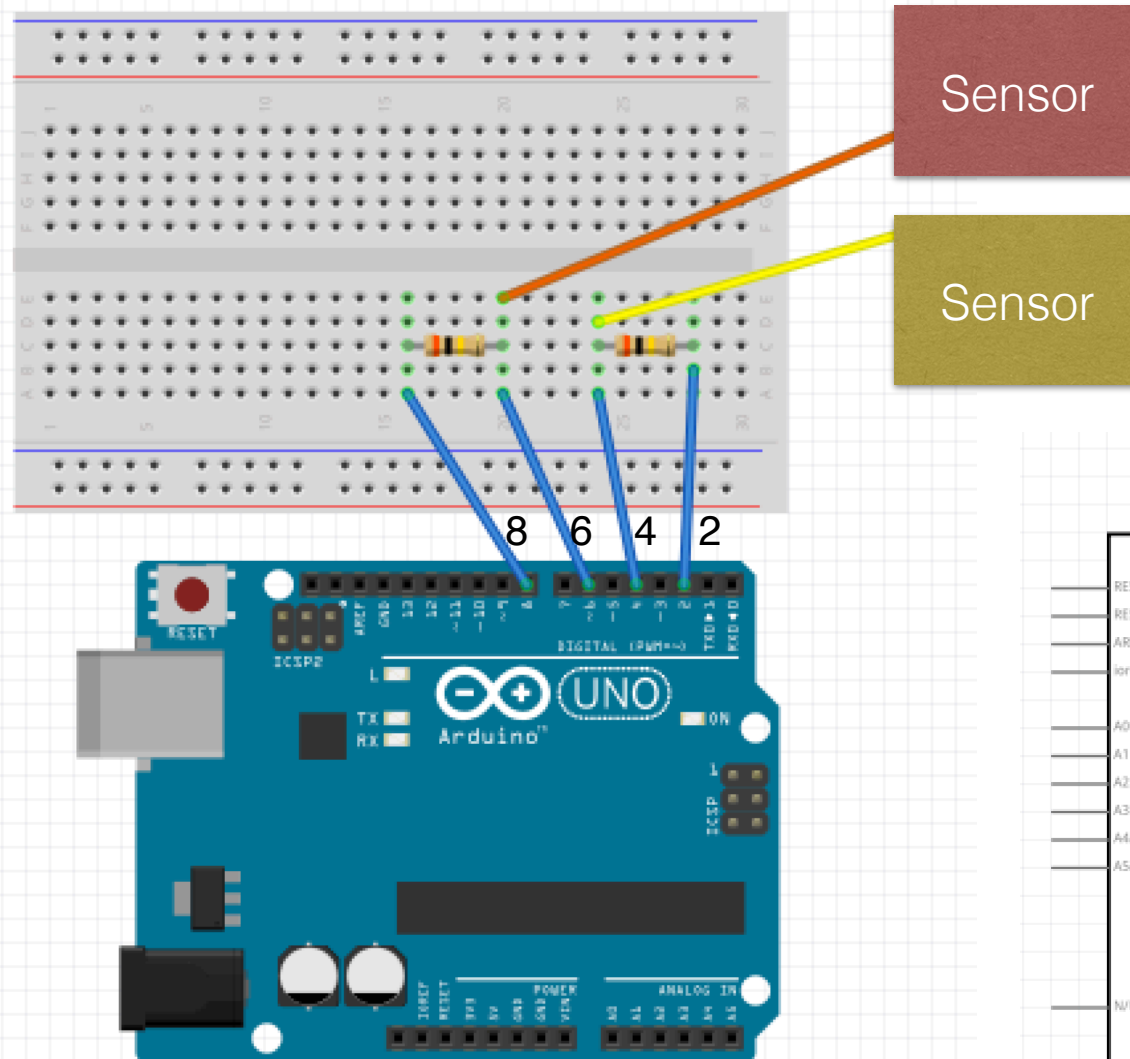
Done Saving.

code: CapacitiveSensor

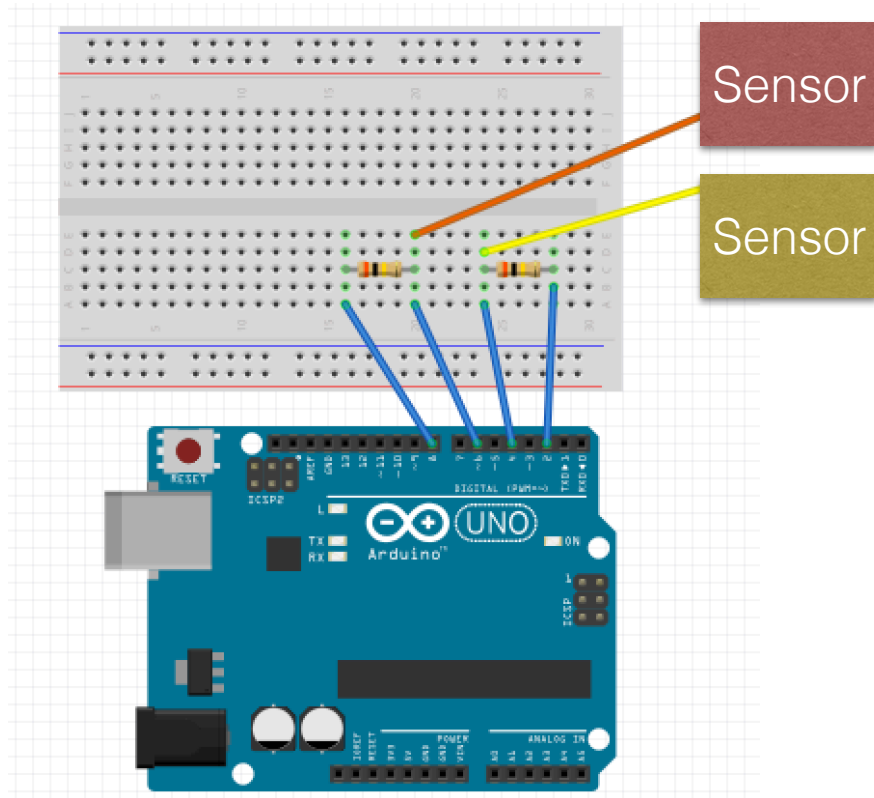
Capacitive Sensors - Circuit



Capacitive Sensors - Circuit



Capacitive Sensor - Circuit



CapacitiveSensor_2

```
#include <CapacitiveSensor.h>
```

```
CapacitiveSensor cs_4_2 = CapacitiveSensor(4,2);  
CapacitiveSensor cs_8_6 = CapacitiveSensor(8,6);
```

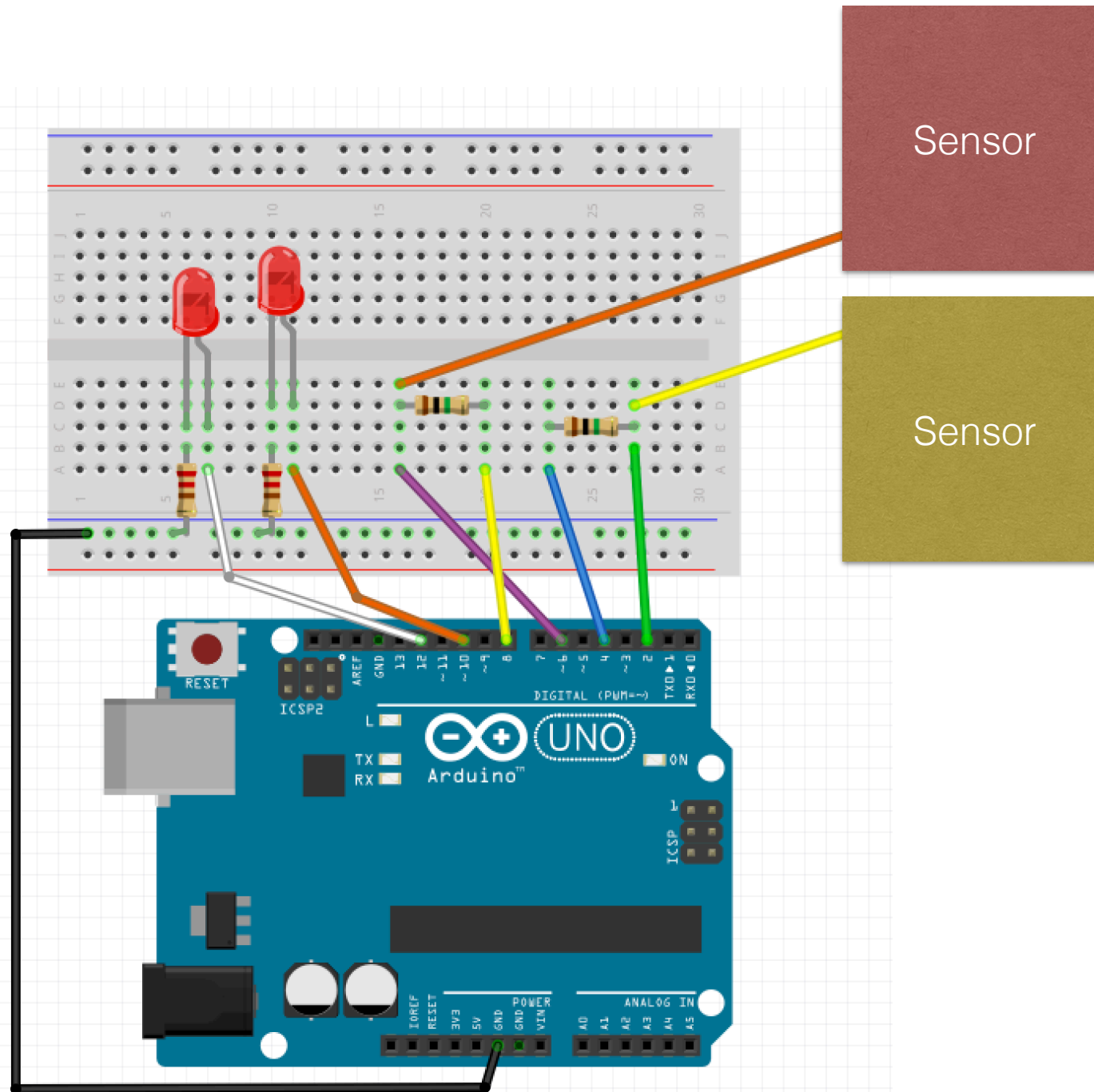
```
void setup()  
{  
  Serial.begin(9600);  
}
```

```
void loop()  
{  
  long total1 = cs_4_2.capacitiveSensor(30);  
  long total2 = cs_8_6.capacitiveSensor(30);  
  
  Serial.print(total1); // print se  
  Serial.print(" ");  
  Serial.println(total2); // print  
  delay(10); // arbitrar  
}
```

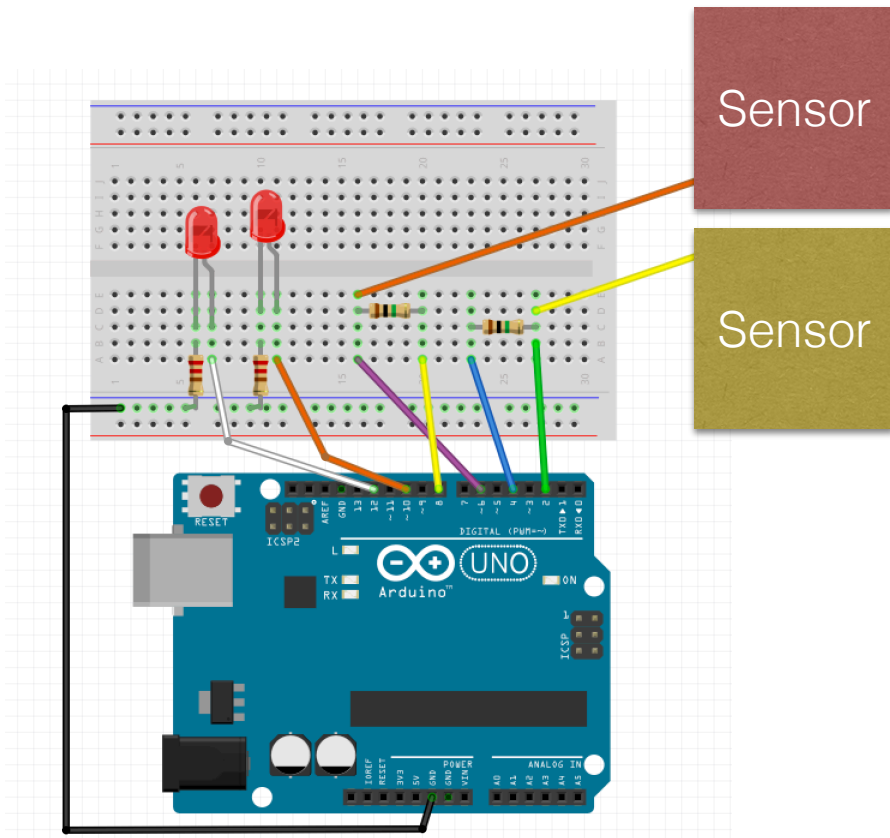
code: CapacitiveSensor_2

Capacitive Sensors and Leds - Circuit

The LEDs
are
connected
to pin10
and pin 12



Capacitive Sensors and Leds - Code



code: CapacitiveSensor_Leds

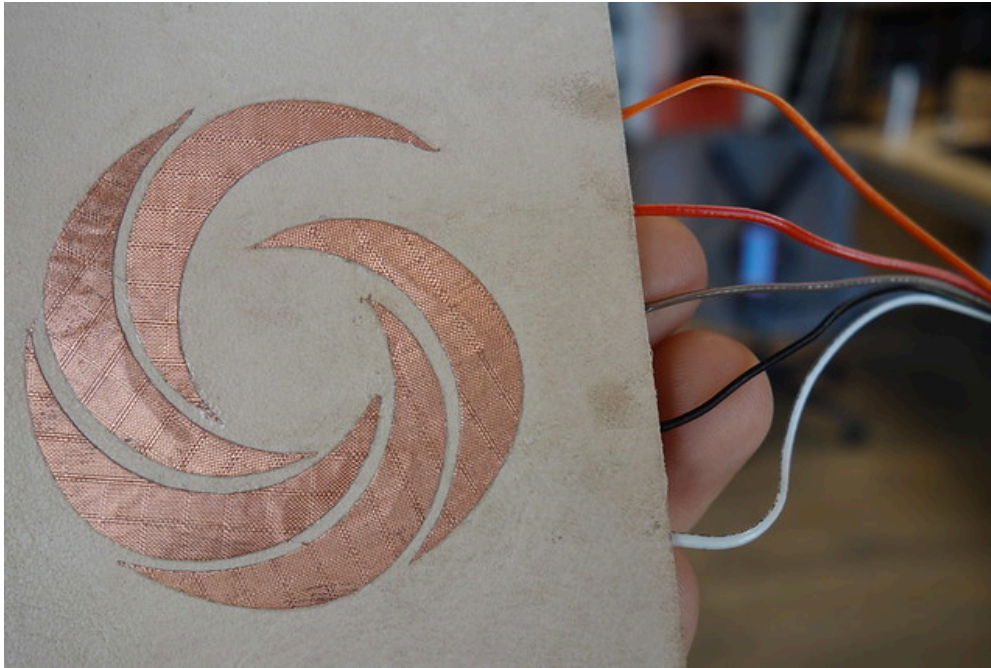
```
CapacitiveSensor_Leds
void setup()
{
  Serial.begin(9600);
  pinMode(led1_pin, OUTPUT);
  pinMode(led2_pin, OUTPUT);
}

void loop()
{
  long total1 = cs_4_2.capacitiveSensor(30);
  long total2 = cs_8_6.capacitiveSensor(30);

  Serial.print(total1);           // print sensor 1
  Serial.print(" ");
  Serial.println(total2);         // print sensor 2
  delay(10);                     // arbitrary delay

  if(total1 > thr & total2 < thr){
    digitalWrite(led1_pin, HIGH);
    digitalWrite(led2_pin, LOW);
  } else if ( total1 < thr & total2 > thr){
    digitalWrite(led1_pin, LOW);
    digitalWrite(led2_pin, HIGH);
  } else if( total1 > thr & total2 > thr){
    digitalWrite(led1_pin, LOW);
    digitalWrite(led2_pin, LOW);
  } else {
    digitalWrite(led1_pin, HIGH);
    digitalWrite(led2_pin, HIGH);
  }
}
```

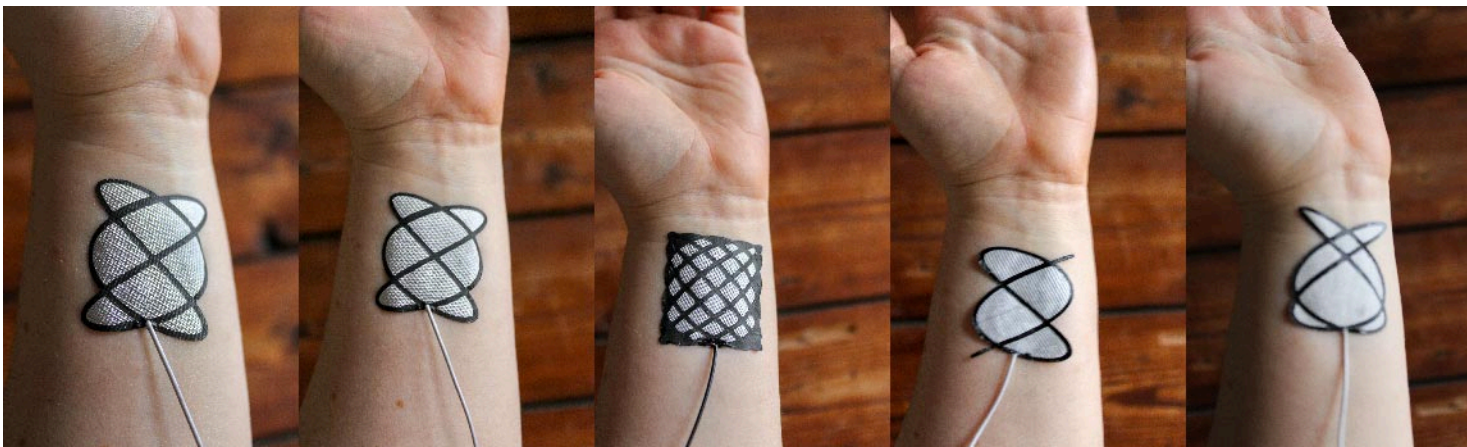

Capacitive Sensors



<https://www.kobakant.at/DIY/?p=6607>



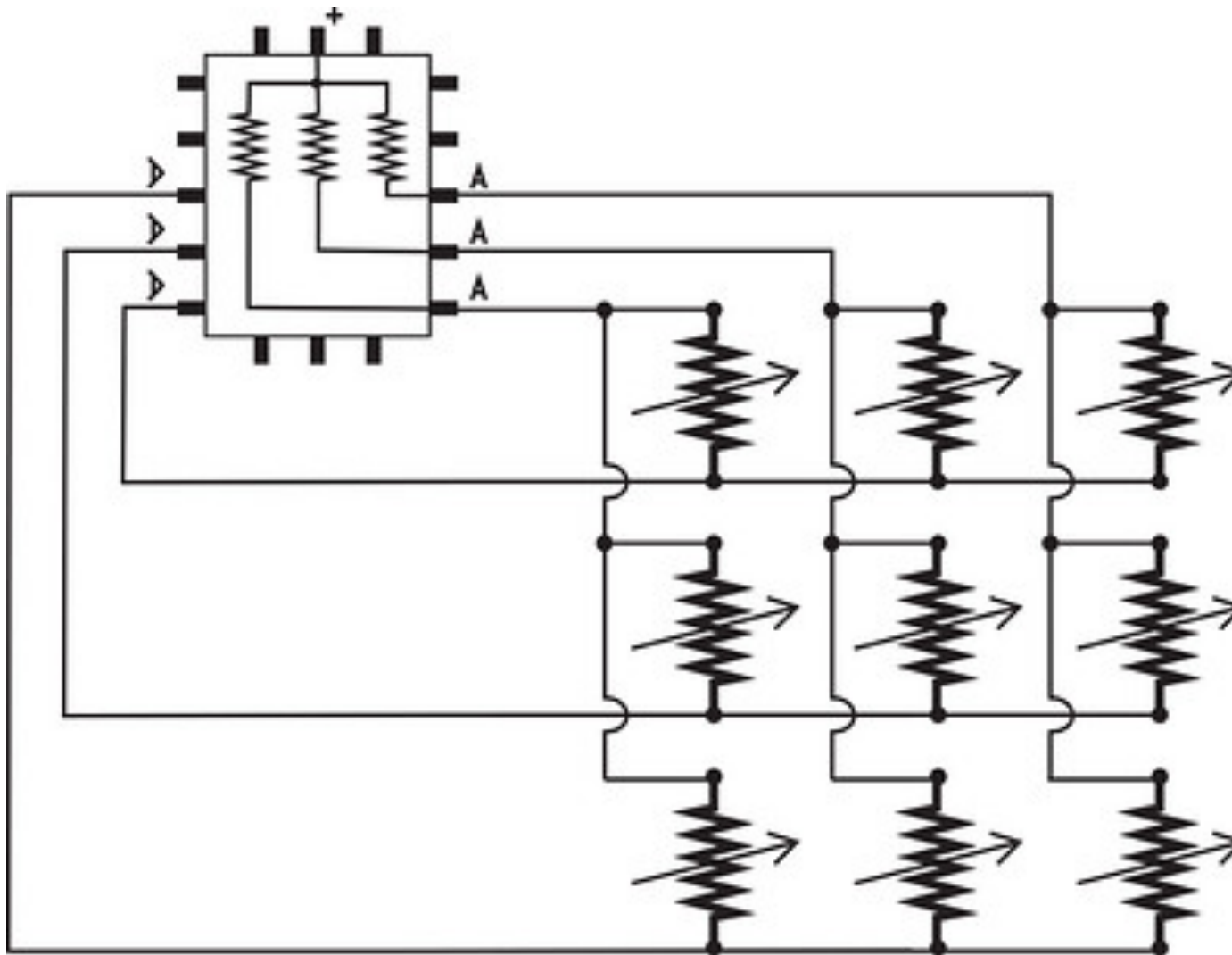
<https://class.textile-academy.org/2019/jessica.stanley/assignments/week12/>



Conductive Paint.

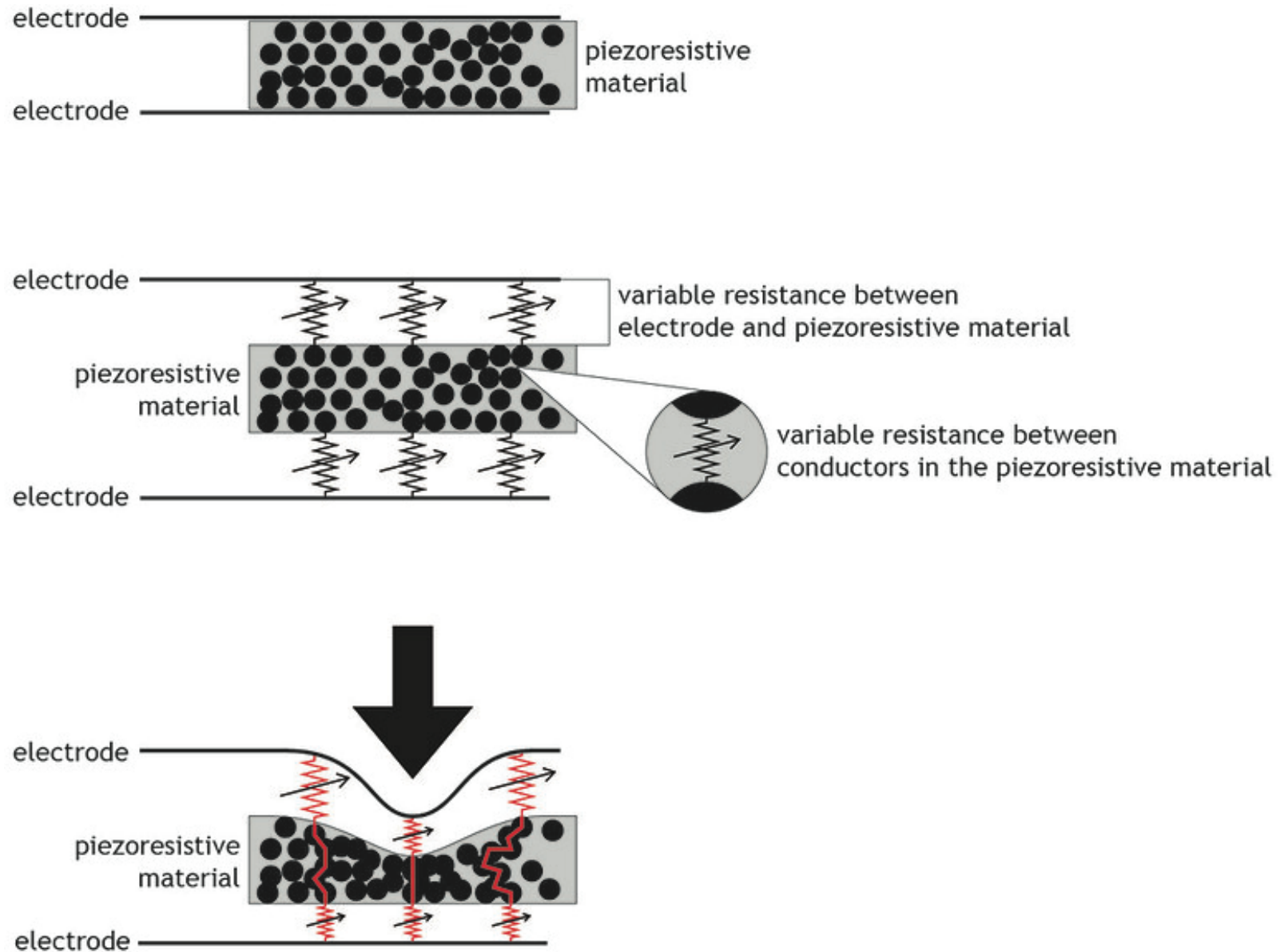
Piezoresistive Matrix

Piezoresistive Matrix

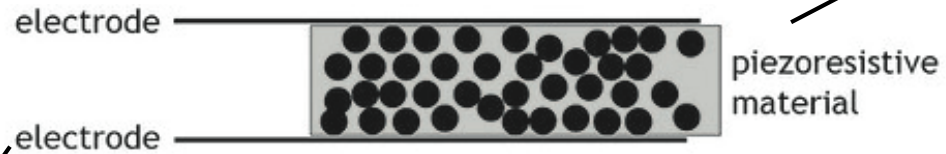


Reference page: <https://www.kobakant.at/DIY/?p=7943>

Piezoresistive Matrix

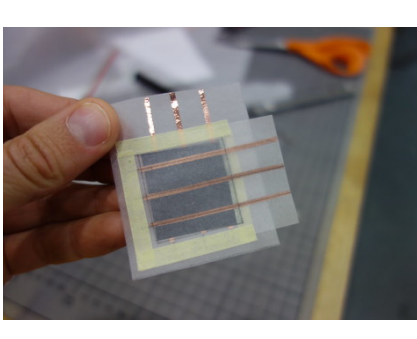
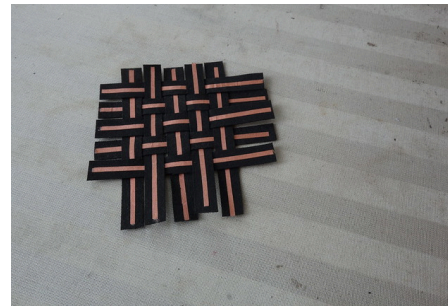
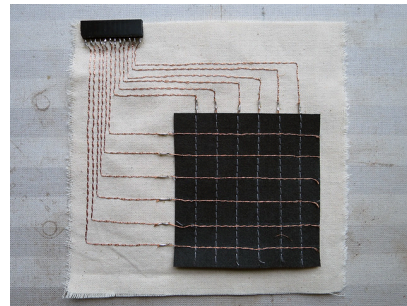
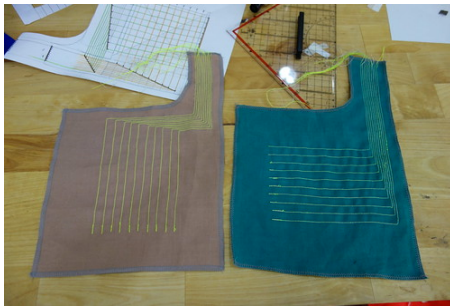


Piezoresistive sensors

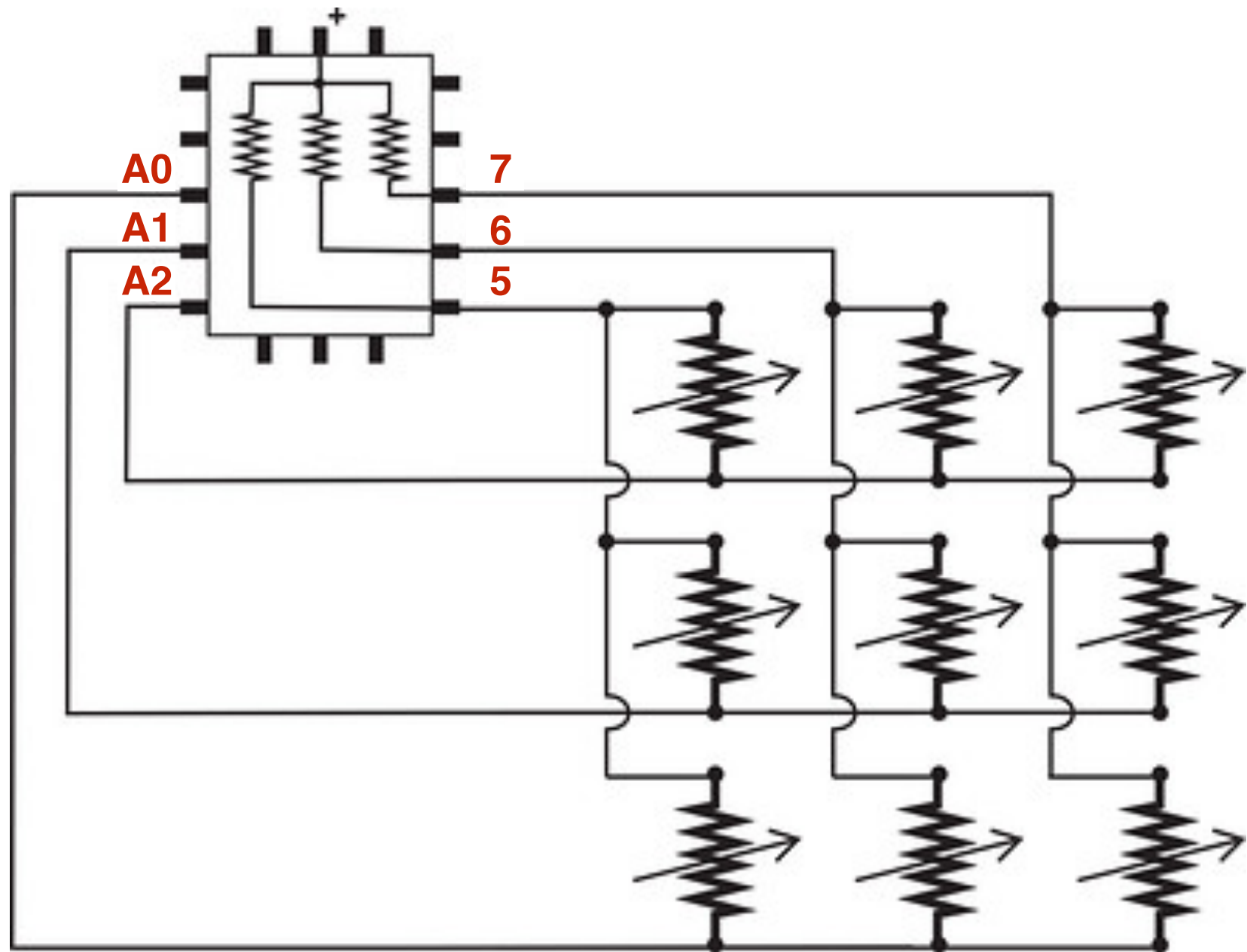


Eeonyx, Velostat, Antistatic foam

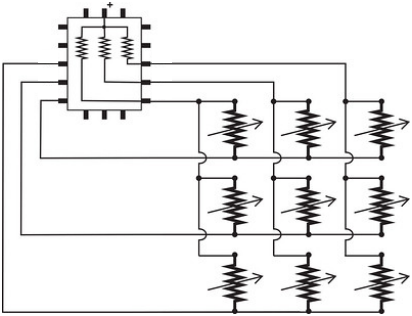
Conductive fabric, Conductive thread,
Copper tape, Copper wires



Arduino and Piezoresistive Matrix



Arduino and Piezoresistive Matrix - Code



code: Matrix

Matrix

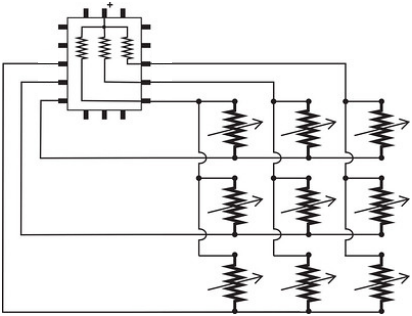
```
//Emma Pareschi- Dec 2020
//Modify example from Pressure Sensor Matrix Code
//parsing through a pressure sensor matrix grid by switching individual
//rows/columns to be HIGH, LOW or INPUT (high impedance) to detect
//location and pressure.
//>> https://www.kobakant.at/DIY/?p=7443

#define numRows 3
#define numCols 3
#define sensorPoints numRows*numCols

int rows[] = {A0, A1, A2};
int cols[] = {5,6,7};
int incomingValues[sensorPoints] = {};

void setup() {
  // set all rows and columns to INPUT (high impedance):
  for (int i = 0; i < numRows; i++) {
    pinMode(rows[i], INPUT_PULLUP);
  }
  for (int i = 0; i < numCols; i++) {
    pinMode(cols[i], INPUT);
  }
  Serial.begin(9600);
}
```

Arduino and Piezoresistive Matrix - Code



```
void loop() {
  for (int colCount = 0; colCount < numCols; colCount++) {
    pinMode(cols[colCount], OUTPUT); // set as OUTPUT
    digitalWrite(cols[colCount], LOW); // set LOW

    for (int rowCount = 0; rowCount < numRows; rowCount++) {
      incomingValues[colCount * numRows + rowCount] = analogRead(rows[rowCount]); /
    } // end rowCount

    pinMode(cols[colCount], INPUT); // set back to INPUT!

  } // end colCount

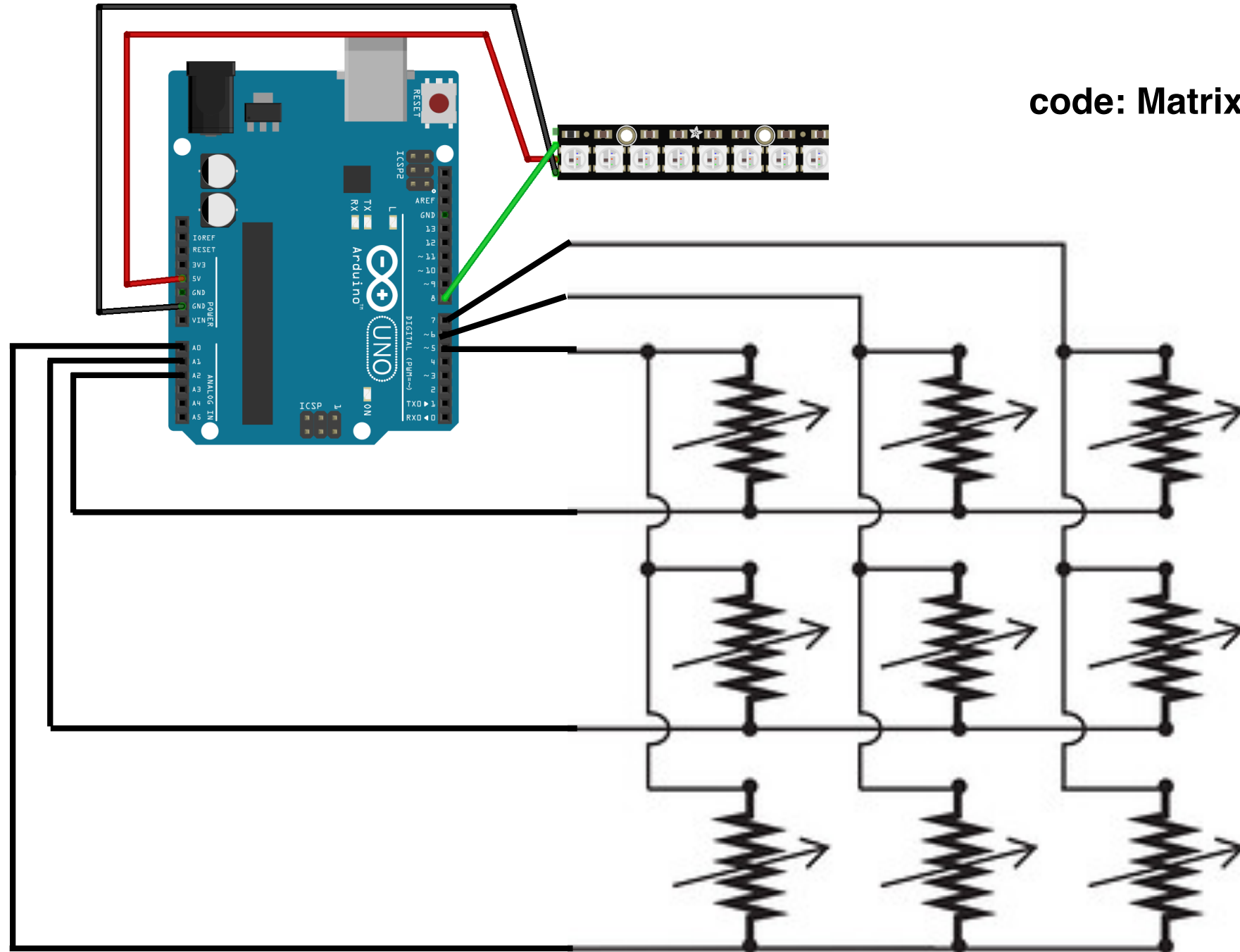
  // Print the incoming values of the grid:
  for (int i = 0; i < sensorPoints; i++) {

    Serial.print(incomingValues[i]);
    if (i < (sensorPoints-1)) {
      Serial.print("\t");
    }
    // Serial.println("");
  }

  Serial.println();
  delay(10);
}
```

code: Matrix

Arduino and Piezoresistive Matrix



code: Matrix_neopixel